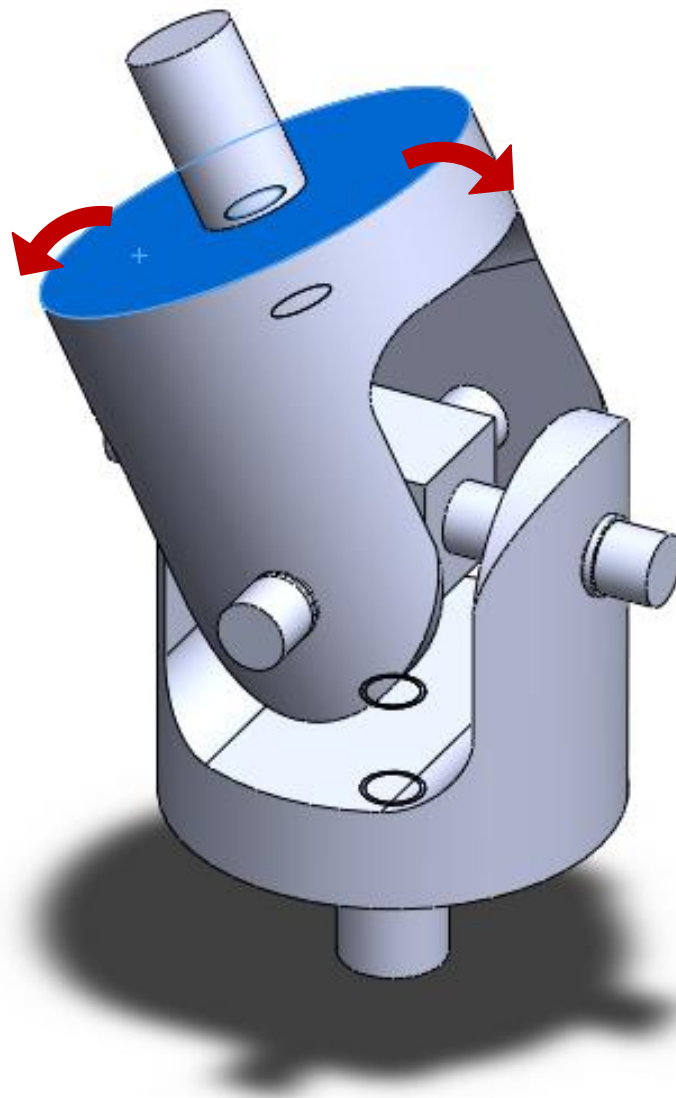




JOINT

(FORMATION IN SETS – DETECTION OF COLLISION)



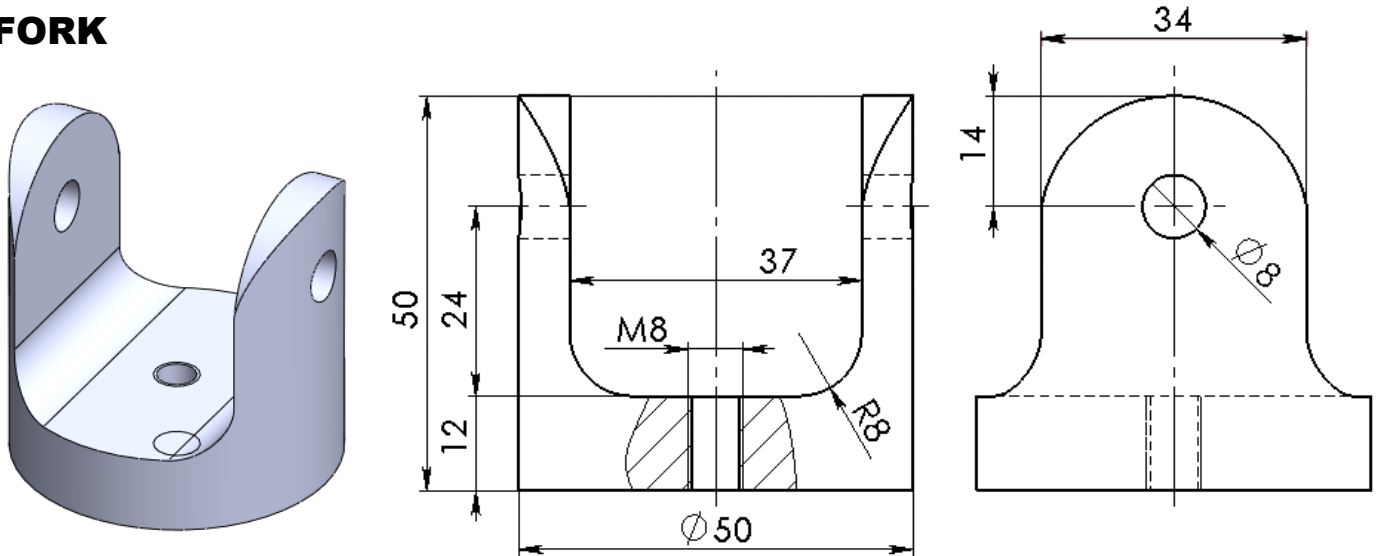
Ing. Hana Vláčilová

(BODY)PART FOR SET OF JOINT



By pictured model form a part of set of joint.
Put the part into user environment Sets.

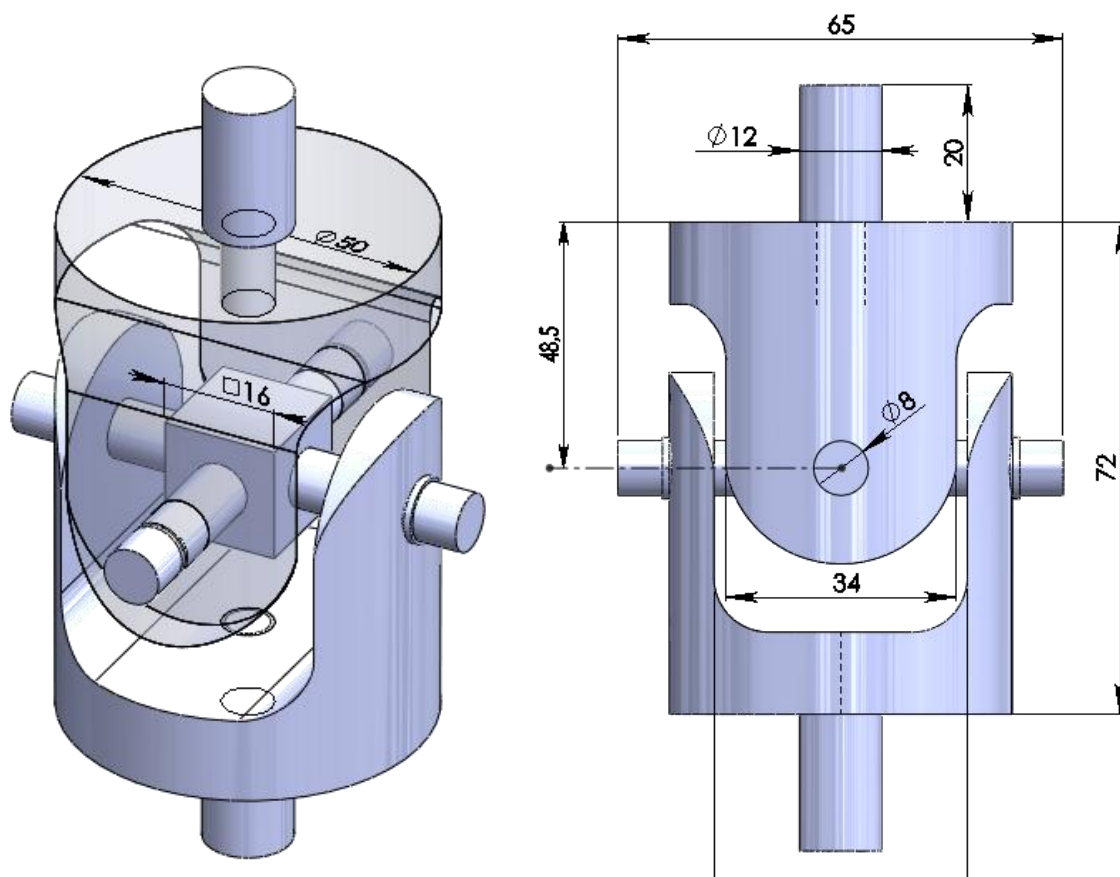
FORK



THE SET OF JOINT



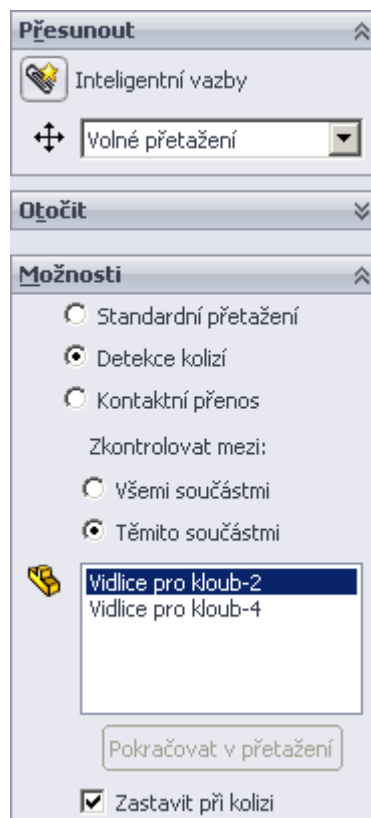
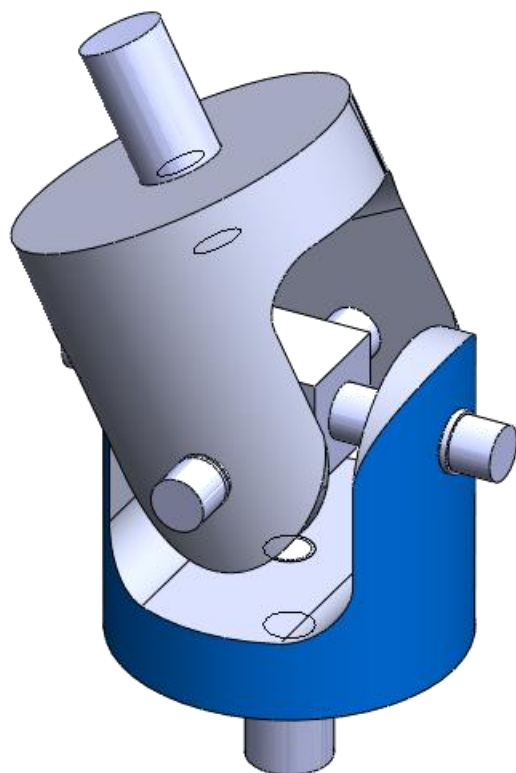
Make the set of joint.
Model new body parts in the set,
Model new parts in the set, parameters ,derive parameters from the fork part.
Keep dimensioned parameters. Propose individually parameters, which are not dimensioned.



DETECTION OF COLLISION



Make detection of collision in the created set. Turn visual and sound control.



Oscillate fork of the joint in two directions

